| Inte     | erference | Search EAS       | T Search History   |                     |         |                  |
|----------|-----------|------------------|--|---------------------|---------|------------------|
| Ref<br># | Hits      | Search Query     | DBs  | Default<br>Operator | Plurals | Time Stamp       |
| L1       | 225       | 348/208.99.ccls. | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:53 |
| L2       | 1719      | 348/143.ccls.    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:53 |
| L3       | 32        | 348/208.3.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 15:50 |
| L4       | 150       | 348/154.ccls.    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:54 |
| L5       | 208       | 396/54.ccls.     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR .                | ON      | 2007/06/29 15:50 |
| L6       | 240       | 396/52.ccls.     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:54 |
| L7       | 1133      | 396/155.ccls.    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:54 |

| L8  | 81   | 396/53.ccls.   | US-PGPUB;  | OR   | ON  | 2007/06/29 14:54 |
|-----|------|--|--|------|-----|------------------|
|     |      |  | USPAT;<br>USOCR;<br>FPRS;  |      |     |                  |
|     |      |  | EPO; JPO;  |      |     |                  |
|     |      |  | DERWENT;<br>IBM_TDB  | ·    |     |                  |
| L12 | 98   | 348/208.1.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR   | OFF | 2007/06/29 14:55 |
| L13 | 73   | 348/208.2.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR   | OFF | 2007/06/29 14:55 |
| L14 | 90   | 348/208.4.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR   | OFF | 2007/06/29 16:00 |
| L30 | 51   | 28 and resonance   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON  | 2007/06/29 15:17 |
| L31 | 74   | 28 and reson\$5  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON  | 2007/06/29 15:17 |
| L37 | 3736 | 1 2 3 4 6 7 8 12 13 14 35 5  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR . | OFF | 2007/06/29 16:01 |
| L38 | 481  | 37 and (reson\$5 or vibrat\$4 or shak\$4 or trembl\$4) same (camera or (imag\$4 near3 (device or apparatus or tak\$3 or pick\$3up or system))) same (pan\$4 or tilt\$4 or rotat\$4 or mov\$3 or pitch) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR   | ON  | 2007/06/29 16:05 |

| L39 | 38 | 37 and (vibrat\$4 or shak\$4 or trembl\$4) same (camera or (imag\$4 near3 (device or apparatus or tak\$3 or pick\$3up or system))) same (pan\$4 or tilt\$4 or rotat\$4 or mov\$3 or pitch) and reson\$5   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR , | ON | 2007/06/29 16:07 |
|-----|----|---|---|------|----|------------------|
| L40 | 2  | ((camera or (imag\$3 near3 (captur\$4 or pick\$3up or tak\$3 or system or device or apparatus))) same (engine or motor or driv\$3) same speed same reson\$4 same (alternative or chang\$3 or modif\$4 or adjust\$4 or modulat\$4 or alter\$3)).clm. | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR . | ON | 2007/06/29 16:10 |
| L41 | 49 | ((camera or (imag\$3 near3 (captur\$4 or pick\$3up or tak\$3 or system or device or apparatus))) same (engine or motor or driv\$3) same speed same reson\$4 same (alternative or chang\$3 or modif\$4 or adjust\$4 or modulat\$4 or alter\$3))      | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/06/29 16:10 |
| L42 | 1  | 37 and 41   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/06/29 16:11 |

| Ref<br># | Hits | Search Query     | DBs  | Default<br>Operator | Plurals | Time Stamp       |
|----------|------|------------------|--|---------------------|---------|------------------|
| L1 .     | 225  | 348/208.99.ccls. | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:53 |
| L2       | 1719 | 348/143.ccls.    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR ·                | ON      | 2007/06/29 14:53 |
| L3       | 32   | 348/208.3.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:53 |
| L4       | 150  | 348/154.ccls.    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR ·                | ON      | 2007/06/29 14:54 |
| L5       | 208  | 396/54.ccls.     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:54 |
| L6       | 240  | 396/52.ccls.     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:54 |
| L7       | 1133 | 396/155.ccls.    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR                  | ON      | 2007/06/29 14:54 |

| L8  | 81   | 396/53.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 14:54 |
|-----|------|---|--|----|-----|------------------|
| L12 | 98   | 348/208.1.ccls.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/06/29 14:55 |
| L13 | 73   | 348/208.2.ccls.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/06/29 14:55 |
| L14 | 90   | 348/208.4.ccls.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/06/29 14:55 |
| L15 | 1485 | "358"/\$.ccls. and (tilt\$4 or pan\$4) with (engine or driver or motor or means)  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | ON  | 2007/06/29 15:18 |
| L16 | 16   | "358"/\$.ccls. and (tilt\$4 or pan\$4) with (engine or driver or motor or means) same (shak\$4 or vibrat\$4 or trembl\$4) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | ON  | 2007/06/29 14:59 |
| L17 | 102  | (pan\$3 or tilt\$3 or surveillance) and resonance near2 frequency same speed same structure                               | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:16 |
| L18 | 176  | camera and (pan\$4 or tilt\$4 or<br>mov\$3) same vibration same (motor<br>or actuator or engine) same noise               | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:00 |

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| L19 | 38  | (camera or (imag\$3 near2 (device or apparatus or system)) or ccd or imager) same (pan\$4 or tilt\$3) same (motor or driver or engine or actuator) and (detect\$4 or measur\$4 or sens\$3 or monitor\$3) with (speed or vibrat\$4 or shak\$4 or resonance) same (adjust\$3 or fix\$3 or modif\$3 or reduc\$3 or chang\$3) near4 (speed or frequency) same (pan\$4 or tilt\$3) same (motor or driver or engine or actuator) | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:02 |
| L20 |     | (pan\$4 or tilt\$4) with motor with camera with (vibrat\$4 or shak\$4)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/06/29 15:02 |
| L21 | 54  | (pan\$4 or tilt\$4) with shak\$4 and detect\$4 near4 speed and camera  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:03 |
| L22 | 309 | camera and (reduc\$4 or minimiz\$4 or cancel\$4 or adjust\$4 or inhibit\$4 or decreas\$3) with (noise\$4 or vibrat\$4 or resonance or shak\$3) same (pan\$4 or tilt\$4) and (adjust\$4 or reduc\$4 or modif\$3 or chang\$3 or decreas\$3) with (motor or means or rotat\$3 or actuator or driv\$3) with (frequenc\$3 or speed)   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:08 |
| L23 | 71  | camera and (sens\$4 or detect\$4 or<br>measur\$3) with (vibrat\$4 or<br>resonance or shak\$4) same (control\$4<br>or reduc\$4 or minimiz\$4 or decreas\$4<br>or slow\$4) with (motor or engine or<br>driver or actuator) same (stabiliz\$4)  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:10 |
| L24 | 40  | 348/208.1.ccls. and (pan\$4 or tilt\$4)  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:13 |

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|-----|-----------|---|--|-----------------|-----|------------------|
| L25 | 171       | pan\$4 with tilt\$4 with after and camera and step\$4 with pan\$4 with tilt\$4                    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR              | ON  | 2007/06/29 15:14 |
| L27 | 20        | (pan\$4 or tilt\$4) with motor with imag\$4 with (vibrat\$4 or shak\$4 or trembl\$4 or resonance) | *US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                   | OR              | OFF | 2007/06/29 15:15 |
| L28 | 3884      | 1 2 3 4 5 6 7 8 12 13 14  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR ,            | ON  | 2007/06/29 15:16 |
| L30 | 51        | 28 and resonance  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR              | ON  | 2007/06/29 15:17 |
| L31 | <b>74</b> | 28 and reson\$5   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR              | ON  | 2007/06/29 15:17 |
| L32 | 690       | ((Tougo with terramoto) or (junji with sato)).in.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR              | ON  | 2007/06/29 15:20 |
| L34 | 35        | 32 and (reson\$4 or vibrat\$4 or trembl\$4 or shak\$4)  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR              | ON  | 2007/06/29 15:20 |
| S1  | 68        | camera and (pan\$3 or tilt\$3 or<br>surveillance) and resonance near2<br>frequency same speed     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR <sub>.</sub> | ON  | 2007/02/07 16:34 |

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| S2 | 98  | (pan\$3 or tilt\$3 or surveillance) and resonance near2 frequency same speed same structure                        | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/29 14:59 |
| S3 | 3   | (pan\$3 or tilt\$3 or surveillance) and resonan\$3 near2 frequency same speed same structure and camera with noise | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/07 16:40 |
| S4 | 694 | ((teramoto with tougo) or (sato with junji)).in.   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/07 16:41 |
| S5 | 15  | S4 and resonan\$3  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/07 16:42 |
| S6 | 3   | camera and (pan ortilt or mov\$3) with<br>resonan\$3 with (motor or actuator or<br>engine) same noise              | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/07 16:44 |
| S7 | 3   | camera and (pan\$4 or tilt\$4 or mov\$3) with resonan\$3 with (motor or actuator or engine) same noise             | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/13 11:27 |
| S8 | 20  | camera and (pan\$4 or tilt\$4 or<br>mov\$3) same resonan\$3 same (motor<br>or actuator or engine) same noise       | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/07 17:31 |

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| S9  | 170  | camera and (pan\$4 or tilt\$4 or<br>mov\$3) same vibration same (motor<br>or actuator or engine) same noise  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR . | ON   | 2007/06/29 15:00 |
| S10 |      | S9 and (modif\$4 or reduc\$4 or adjust\$4 or control\$4 or decreas\$4) near3 speed   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON   | 2007/02/08 10:22 |
| S11 | 211  | 348/208.99.ccls.   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON . | 2007/06/29 14:53 |
| S12 | 13   | 348/208.99.ccls. and resonance   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON   | 2007/02/08 10:29 |
| S13 | 101  | 348/208.99.ccls. and (vibration or (natural adj frequenc\$3))  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON   | 2007/02/08 10:33 |
| S14 | 1987 | camera and (pan\$4 or tilt\$3 or rotat\$3) same (motor or driver or engine or actuator) with (detect\$4 or determin\$4 or measur\$4) with (speed or vibrat\$4) | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR . | ON   | 2007/02/08 10:35 |
| S15 | 1473 | camera and (pan\$4 or tilt\$3 or<br>rotat\$3) same (motor or driver or<br>engine or actuator) with (detect\$4 or<br>measur\$4) with (speed or vibrat\$4)       | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON   | 2007/02/08 10:36 |

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| S16 | 443 | camera same (pan\$4 or tilt\$3 or<br>rotat\$3) same (motor or driver or<br>engine or actuator) with (detect\$4 or<br>measur\$4) with (speed or vibrat\$4)  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/08 10:37 |
| S17 | 351 | S16 not tsikos not knowles not zhu   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/08 10:39 |
| S18 | 63  | camera same (pan\$4 or tilt\$3 or rotat\$3) same (motor or driver or engine or actuator) with (detect\$4 or measur\$4) with (speed or vibrat\$4) same (adjust\$3 or fix\$3 or modif\$3 or reduc\$3 or chang\$3) near4 (speed or frequency)   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/08 10:49 |
| S19 | 62  | S18 not tsikos not knowles not zhu   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/08 11:26 |
| S20 | 16  | (camera or (imag\$3 near2 (device or apparatus or system)) or ccd or imager) same (pan\$4 or tilt\$3) same (motor or driver or engine or actuator) with (detect\$4 or measur\$4) with (speed or vibrat\$4) same (adjust\$3 or fix\$3 or modif\$3 or reduc\$3 or chang\$3) near4 (speed or frequency)   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/08 11:04 |
| S21 | 34  | (camera or (imag\$3 near2 (device or apparatus or system)) or ccd or imager) same (pan\$4 or tilt\$3) same (motor or driver or engine or actuator) and (detect\$4 or measur\$4 or sens\$3 or monitor\$3) with (speed or vibrat\$4 or shak\$4 or resonance) same (adjust\$3 or fix\$3 or modif\$3 or reduc\$3 or chang\$3) near4 (speed or frequency) same (pan\$4 or tilt\$3) same (motor or driver or engine or actuator) | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/06/29 15:00 |

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|-----|------|--|--|----|-----|------------------|
| S22 | 3    | "57208547"   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 11:07 |
| S23 | 12   | "2242753"  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 11:07 |
| S24 | . 7  | ("3984628"   "4516156"   "5109278"  <br>"5111288"   "5315633"   "5570177"  <br>"5572317").PN.  | US-PGPUB;<br>USPAT;<br>USOCR   | OR | OFF | 2007/02/08 11:13 |
| S25 | 18   | ("3984628").URPN.  | USPAT  | OR | OFF | 2007/02/08 11:13 |
| S26 | 92   | 348/208.1.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 11:21 |
| S27 | 38   | 348/208.1.ccls. and (pan\$4 or tilt\$4)  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:13 |
| S28 | 289  | camera and (reduc\$4 or minimiz\$4 or cancel\$4 or adjust\$4 or inhibit\$4 or decreas\$3) with (noise\$4 or vibrat\$4 or resonance or shak\$3) same (pan\$4 or tilt\$4) and (adjust\$4 or reduc\$4 or modif\$3 or chang\$3 or decreas\$3) with (motor or means or rotat\$3 or actuator or driv\$3) with (frequenc\$3 or speed) | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:07 |
| S29 | 183  | S28 not tsikos not knowles not zhu   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 11:27 |

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| S30 | 29   | 348/208.3.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 14:53 |
| S31 | 1    | "6982746".pn. and shak\$3 with (pan\$1tilt or pan\$4 or tilt\$4)   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 12:12 |
| S32 | 1    | 10/696281  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 12:12 |
| S33 | 14.  | ("20010012059"   "20030035053"  <br>"4992855"   "5210563"   "5237365"  <br>"5502484"   "5585875"   "5587737"  <br>"5905848"   "5978599"   "5990942"  <br>"6173121"   "6501503").PN. OR<br>("6982746").URPN.                  | US-PGPUB;<br>USPAT;<br>USOCR   | OR | OFF | 2007/02/08 14:34 |
| S34 | · 64 | camera and (sens\$4 or detect\$4 or measur\$3) with (vibrat\$4 or resonance or shak\$4) same (control\$4 or reduc\$4 or minimiz\$4 or decreas\$4 or slow\$4) with (motor or engine or driver or actuator) same (stabiliz\$4) | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:09 |
| S35 | 1640 | 348/143.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 14:53 |
| S40 | 337  | 348/155.ccls.  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/17 13:20 |

| S41 | 225 | 306/E2 colo  | US-PGPUB;  | OR   | ON | 2007/02/09 15:17 |
|-----|-----|--|--|------|----|------------------|
| 541 | 223 | 396/52.ccls.   | USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB              | OK . | ON | 2007/02/08 15:17 |
| S42 | 80  | 396/53.ccls.   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/08 15:17 |
| S43 | 206 | 396/54.ccls.   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/06/29 14:54 |
| S44 | 2   | camera and (sens\$4 or detect\$4 or measur\$3) with (vibrat\$4 or resonance or shak\$4) with speed with (motor or engine or driver or actuator) same (control\$4 or reduc\$4 or minimiz\$4 or decreas\$4 or slow\$4) with (motor or engine or driver or actuator) same (stabiliz\$4) | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/08 15:42 |
| S45 | 84  | camera and (sens\$4 or detect\$4 or measur\$3) with (vibrat\$4 or resonance or shak\$4) with speed with (motor or engine or driver or actuator) same (control\$4 or reduc\$4 or minimiz\$4 or decreas\$4 or slow\$4) with (motor or engine or driver or actuator)                    | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR . | ON | 2007/02/08 16:08 |
| S46 | 50  | (pan\$4 or tilt\$4) with shak\$4 and detect\$4 near4 speed and camera  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/06/29 15:03 |
| S47 | 3   | (pan\$4 or tilt\$4) with shak\$4 and detect\$4 near4 speed with motor and camera   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/08 16:20 |

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| S48 | 7   | (pan\$4 or tilt\$4) with vibrat\$4 and detect\$4 near4 speed with motor and camera   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 16:43 |
| S49 | 10  | (pan\$4 or tilt\$4) with vibrat\$4 and (detect\$4 or measur\$4) near4 (speed or frequency) with motor and camera   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/08 16:48 |
| S50 | 23  | (pan\$4 or tilt\$4) with motor with camera with (vibrat\$4 or shak\$4)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/06/29 15:02 |
| S51 | 16  | (pan\$4 or tilt\$4) with motor with imag\$4 with (vibrat\$4 or shak\$4)  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/06/29 15:14 |
| S52 | 208 | camera and (sens\$4 or detect\$4 or measur\$3) with (frequency or speed) with (driver or motor or driving or engine or actuator) same (control\$4 or reduc\$4 or minimiz\$4 or decreas\$4 or slow\$4) with (motor or engine or driver or actuator) same (vibrat\$4 or shak\$3) | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/09 09:47 |
| S53 | 138 | S52 and (@ad<"20030626" or<br>@rlad<"20030626")  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/09 10:13 |
| S54 | 19  | ejima.in. and public   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/09 12:22 |

| CEE | 4.4 | "5976020"     | LIC DCDUD  | OB   | ON | 2007/02/00 12:22 |
|-----|-----|---------------|--|------|----|------------------|
| S55 | 14  | "5876929"     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/09 12:23 |
| S56 | 2   | "6876929"     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/09 12:23 |
| S57 | . 6 | "5826929"     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/09 12:23 |
| S58 | 513 | "5876969"     | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/09 12:23 |
| S59 | 0   | "5876969.pn." | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/09 12:23 |
| S60 | 2   | "5876969".pn. | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR   | ON | 2007/02/09 12:24 |
| S61 | . 2 | "5826969".pn. | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR · | ON | 2007/02/09 12:24 |

| S62      | 20   | limb near3 dark\$4   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2007/02/09 15:23 |
|----------|------|--|---|----|-----|------------------|
| S63      | 39   | limb near3 dark\$4   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/09 15:23 |
| S64      | 63   | limb near3 darken\$4   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/12 11:52 |
| S65      | 1375 | lens same shad\$4 near3 correct\$4   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/12 11:54 |
| S66      | 434  | S65 and camera   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/12 11:54 |
| S68      | 66   | (nelson with hernandez).xa.  | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | OFF | 2007/02/12 12:08 |
| \$83     | 19   | ("4583186"   "4734783"   "4816663"   "4845551"   "4945406"   "4979042"   "5134573"   "5253083"   "5303056"   "5343302"   "5461440"   "5659813"   "5822453"   "6141046"   "6181830"   "6323934"   "6339466").PN. OR ("6670988").URPN. | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | OFF | 2007/02/12 14:49 |
| S86      | 50   | "4945406"  | USPAT   | OR | OFF | 2007/02/12 15:24 |
| S13<br>9 | 211  | 348/208.99.ccls.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2007/06/29 14:55 |
| S14<br>0 | 150  | 348/208.99.ccls. and (shak\$4 or vibrat\$4 or resonance)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/17 13:07 |

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| S14<br>1 | 77  | 348/208.99.ccls. and (shak\$4 or vibrat\$4 or resonance) and (pan\$4 or tilt\$4)   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | ON  | 2007/02/17 13:08 |
| S14<br>2 | 11  | S141 and resonance   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | ON  | 2007/02/17 13:09 |
| S14<br>3 | 92  | 348/208.1.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/06/29 14:55 |
| S14<br>4 | 4   | S143 and resonance   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | ON  | 2007/02/17 13:09 |
| S14<br>5 | 71  | 348/208.2.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/02/17 13:10 |
| S14<br>6 | 29  | 348/208.3.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/02/17 13:19 |
| S14<br>7 | 80  | 348/208.4.ccls.  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/02/17 13:20 |
| S14<br>9 | 134 | (resonance and (motor or driv\$3 or engine or actuator) and (camera or imag\$3 near1 (device or apparatus or system) or imager) and (frequenc\$3 or speed or acceleration or pulse or velocity) and (angle or position)).clm.      | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/17 13:26 |
| S15<br>0 | 6   | (resonance same (motor or driv\$3 or engine or actuator) same (camera or imag\$3 near1 (device or apparatus or system) or imager) same (frequenc\$3 or speed or acceleration or pulse or velocity) same (angle or position)). clm. | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/17 13:27 |

| S15<br>1 | 0   | pan\$4 and tilt\$4 and camera and<br>motor near6 pan\$4 and mtor near6<br>tilt\$4 and motor near5 (after or off)<br>and @ad<"20030623"  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/02/20 14:11 |
|----------|-----|---|--|----|-----|------------------|
| S15<br>2 | 2   | ("5978016").PN.   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/02/20 14:11 |
| S15<br>3 | 60  | pan\$4 and tilt\$4 and camera and<br>motor near6 pan\$4 and motor near6<br>tilt\$4 and motor near5 (after or off)<br>and @ad<"20030623" | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | OFF | 2007/02/20 14:13 |
| S15<br>4 | 7   | ("3984628"   "4516156"   "5109278"  <br>"5111288"   "5315633"   "5570177"  <br>"5572317").PN.   | US-PGPUB;<br>USPAT;<br>USOCR   | OR | OFF | 2007/02/20 14:36 |
| S15<br>5 | 0   | perform\$4 with pan\$4 with after with tilta\$4 and camera  | US-PGPUB;<br>USPAT;<br>USOCR   | OR | OFF | 2007/02/20 17:44 |
| S15<br>7 | 8   | "6297870"   | US-PGPUB;<br>USPAT;<br>USOCR   | OR | OFF | 2007/02/20 17:51 |
| S16<br>0 | 4   | "6930718"   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/20 18:17 |
| S16<br>1 | 4   | "6833861"   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/02/21 09:06 |
| S16<br>2 | 161 | pan\$4 with tilt\$4 with (after) and camera and step\$4 with pan\$4 with tilt\$4  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2007/06/29 15:13 |

| S16<br>3 | 140 | pan\$4 with tilt\$4 with first with second<br>and camera and step\$4 with pan\$4<br>with tilt\$4                | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/21 11:32 |
|----------|-----|---|--|----|----|------------------|
| S16<br>4 | 81  | S163 and @ad<"20021113"   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB                    | OR | ON | 2007/02/21 11:28 |
| S16<br>5 | 1   | pan\$4 with tilt\$4 with different near3<br>(period or time) and camera and<br>step\$4 with pan\$4 with tilt\$4 | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/21 11:33 |
| S16<br>6 | 0   | pan\$4 with tilt\$4 with "not" with<br>simultaneous\$3 and camera and<br>step\$4 with pan\$4 with tilt\$4       | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/21 11:34 |
| S16<br>7 | 60  | pan\$4 with tilt\$4 with simultaneous\$3<br>and camera and step\$4 with pan\$4<br>with tilt\$4                  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/21 13:39 |
| S16<br>8 | 0   | pan\$4 with tilt\$4 with "not" near4 simultaneous\$3 and camera   | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/21 11:40 |
| S16<br>9 | 12  | pan\$4 with tilt\$4 with different near4 time and camera  | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2007/02/21 11:40 |

| S17<br>0 | "6816288".pn. and imag\$4 | US-PGPUB;<br>USPAT;<br>USOCR;<br>FPRS;<br>EPO; JPO;<br>DERWENT; | OR | ON | 2007/02/21 13:39 |
|----------|---------------------------|---|----|----|------------------|
|          | ,                         | IBM_TDB   |    |    |                  |